## Extreme wave observations in Deep Ocean

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## Brief description of motivation for study/application

- Extreme wave events occur in deep ocean but existing wave buoy networks are mostly confined to oceans in the vicinity of coast
- There are numerous moored buoys (DART, TAO/TRITON, NDBCmet buoys, etc.) and drifters (ARGO, etc.) without wave sensors that can be utilized to measure waves in the future
- Sensing buoy motion to detect mean wave properties seems feasible, but how about detecting extreme waves?



Swail et al. 2009

http://www.ndbc.noaa.gov/

#### Brief description of the methodology used in the study/application

- Attach a GPS wave sensor to an existing Met-Ocean moored buoy
  - K-TRITON buoys at JAMSTEC JKEO and NKEO stations
  - Validate wave observation with drifting wave buoy and 3G wave hind-cast simulations
- Estimate basic statistical properties of observed waves
- Case study of large amplitude waves Horizontal motion
  - Freak waves over 10m (two events of 12 and 13 m wave height)
  - Extreme but not freak waves (three events around 20 m wave height)
- Monte-Carlo simulation using High-Order Spectral Method





#### Summary of conclusions

- Wave was successfully observed attaching a pointpositioning GPS sensor to existing deep ocean met-ocean mooring buoys in 2009 (3 months) and 2012-2013 (3 months and 9 months)
- Statistical properties of observed buoy motion after appropriate filtering conform with the classical description of ocean waves
- Extreme waves including freak waves were successfully observed demonstrating the feasibility of GPS sensor without reference point
- Horizontal movement of the buoy indicate orbital motion close to group velocity for some large waves

## Principle of GPS wave sensing

- Wave sensing with point-positioning GPS (JAXA: Yamaguchi et al, 2005)
  - High-pass filter: distinct frequency bands of wave and GPS noise spectrum (Harigae et al. 2005)
  - Noise due to change in number of satellites
  - Orbital motion simulator
  - Ocean testing off Shikoku Island



Error source	Range(1σ)	時定数	
ephemeris	~3m	~1hr	
Satellite clock	~3m	~5min	
ionosphere	~9m	~10min	
troposphere	~2m	~10min	
multipath	~3m	~100sec	
GPS receiver	~1m	white noise	



## **Observation platforms – JAMSTEC K-TRITON Buoy**

No.2

- Drifting buoy
  - Disk; reduce Roll by viscous No.4 effect (Katayama et al. 2007).
  - No.1 with wind sensor
  - No.3 & 6 improved stability





#### Extracting wave signal from point-positioning GPS



#### Response amplitude operator of K-TRITON buoy (heave, surge, pitch)



## **Observation points and periods**

- JKEO (JAMSTEC Kuroshio Extension Observatory)
  - Deep ocean (5400m);
    38.1N, 146.4E, slack
- NKEO (New KEO)
  - Deep ocean (5700m);
    33.8N, 144.8E, slack
- Kouzu Island
  - Shallow (75m), slack
- Hiratsuka observational tower
  - Shallow (20m); tower (wave gauge, wind sensors)
- Kashiwa roof top
  - Fixed position



From JAMSTEC

Buoy platforms	Location	Period	Status	
Drifter No.1	Hiratsuka	09/7/14-2009/8/10		
	JKEO	2009/8/29-2009/9/2	LOST	
K-TRITON No.1	JKEO	2009/8/30-(12/6)2010/9/18	Retrieved	
Drifter No.2	Kashiwa	2010/7/21-2010/8/11		
	Hiratsuka	2010/8/23-2010/12/21	Loct	
	Mirai	2011/2/12-2011/2/23	LOST	
	JKEO	2011/2/23-2011/2/26		
K-TRITON No.2	Kashiwa	2010/11/5-2011/1/4		
	Mirai	2010/2/12-2010/2/23	Retrieved	
	JKEO	2011/2/23-(3/3) 2012/6/22		
KOUZU	Nishichiba	2010/12/17-2010/12/24		
	Kouzu-port	2011/1/11-2011/1/23		
	Kouzu	2011/1/23-2011/3/4	Retrieved	
	Kouzu	2011/6/31-2012/3末		
	Kouzu	2012/6/30-2012/3/12		
	Kouzu	2013/9/ -	In Operation	
Drifter No.3	Kashiwa	2011/2/25-2011/3/2		
	Kouzu	2011/3/11-2011/4/26	retrieved	
K-TRITON No.3	JKEO	2012/6/23-(2012/9/17)	Retrieved	
K-TRITON No.4	NKEO	2012/6/20-2013/3/	Retrieved	
	JKEO	2014/4/ -	Planned	

#### Cross validation: Hiratsuka Tower, Drifting buoy, K-TRITON



#### Statistics of wave measurements from the K-TRITON buoy



## Observation-model comparison (JKEO)

Moored buoy observation compares fairly well with the model



#### NKEO Observation 2012 June – 2013 March







#### Effect of tethering on pitching/rolling motion



#### NKEO ~20 m wave height events – *horizontal motion*



Line segments indicate 20-minute buoy tracks

#### 2013.1.14 NKEO extreme wave observation



雨。沖縄で30mm/1h以上の雨となり1月 の1位の値を更新した所も。東日本は高 気圧圏内で晴れて気温が平年よりも高め。で初雪。最深積雪は横浜13cm、東京8cm。北日本を中心に293地点で真冬日。 岩手県で震度4。

風が強く、関東南部中心に雪。千葉県銚 子で最大瞬間風速38.5m/s。横浜・東京

太平洋側は東海・関東を中心に概ね晴れ。

#### 2013.1.14 Hmax=17.7m; time-series (filtered)



#### Horizontal motion; filtered vs. un-filtered records



#### 2012.10.4 NKEO extreme wave obseravtion



台風第19号の北上に伴い、八丈島西見で 最大瞬間風速30.5m/s、57mm/1hの雨。関 東は南岸の前線により雨、西日本は移動 性高気圧に覆われ晴れ。東海と北海道の 一部で気温上昇。 台風第19号は北上を続け温帯低気圧に。 関東~東北の太平洋岸は台風の北上に 伴って風が強まり千葉県銚子で最大風速 20.7m/s。晴れた東海を中心に21地点で 真夏日。 北日本上空に寒気を伴った気圧の谷が通 過し、大気の状態が不安定。北陸~東北 では積乱雲が発達し、秋田県で突風、新 潟県の海上で竜巻発生。山形県鶴岡市荒 沢で59mm/1hの雨。

#### Waves of 20 m height; horizontal motion



#### NKEO 2012.10.3 – 10.6 : 95 x 20min records



#### Particle motion at the free surface (Tank: L10m, D60cm, W80cm)



#### 2012 Takahashi, thesis U-Tokyo

#### Modulational instability and particle velocity



At most, 0.7 times group velocity; if the wave is breaking,

it should reach the phase speed

80

100

120

140

#### JKEO Observation 2009 August - December





#### JKEO 2009.10 freak wave – Freakish Sea Index

#### 2009.10.26 19:00 (UTC)



#### Surface elevation from directional spectrum



#### Monte Carlo Simulation (100 periods x 10 ) with High-Order Spectral Method



2013 Fujimoto, thesis UTokyo

#### Geometry of freak waves – linear vs. nonlinear



## **Concluding remarks**

- Wave was successfully observed attaching a point-positioning GPS sensor to existing deep ocean met-ocean mooring buoys in 2009 (3 months) and 2012-2013 (3 months and 9 months)
- Statistical properties of observed buoy motion after appropriate filtering conform with the classical description of ocean waves
- Extreme waves including freak waves were successfully observed demonstrating the feasibility of GPS sensor without reference point
- Horizontal movement of the buoy indicate orbital motion close to group velocity for some large wave
  - Simultaneous accelerometer based observation will complement the GPS observation (see Collins' presentation in this WS)
- HOSM realization revealed relationship between nonlinearity and directional spreading

#### Wave shape around peak records ak=0.22



#### **Regional Operational Wave Model**

#### WAVEWATCHIII™

- Sin, Sds: Tolman-Chalikov, Snl: DIA
- 2 tiered nested model
  1degree(Pacific) → 1/4度(East of Japan)
  1degree (Pacific) → 1/10度(NKEO)

#### Wind

 $NOGAPS(Pacific) \rightarrow MSM(Regional)$ 



# In operation since 2009 April



