

## An event of „Parametric Rolling“ onboard RV “Polarstern”

Thomas Bruns <sup>1</sup>

Susanne Lehner <sup>2</sup> Xiao-Ming Li <sup>2</sup>

Katrin Hessner <sup>3</sup> Wolfgang Rosenthal <sup>4</sup>

<sup>1</sup> DWD, Hamburg, Germany

<sup>2</sup> DLR, Oberpfaffenhofen, Germany

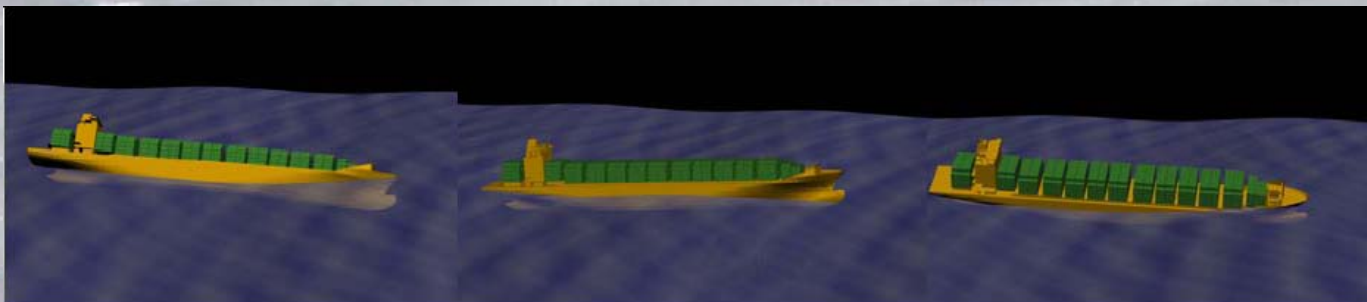
<sup>3</sup> OceanWaveS, Lüneburg, Germany

<sup>4</sup> GAUSS, Bremen, Germany

# Motivation (1)

## „Parametric Rolling”

- A serious problem for large container ships
- Is it possible to set up a warning system based on remote sensing and wave forecasts?





# Motivation (2)



## Project „PaRoI“

(GMES-DeMarine Security)

GMES = *Global Monitoring for Environment and Security*

## Application of Remote Sensing Technology for Ship Damage Prevention

- lead by German Aerospace Center, Oberpfaffenhofen
- GAUSS mbH, Bremen
- OHB-System AG, Bremen
- Deutscher Wetterdienst, Hamburg
- Federal Waterways Engineering and Research Institute, Hamburg



# Methodology

- **Installation of a „WaMoS“ Wave Radar System onboard RV „Polarstern“**
- **Antarctic Expedition Oct 2008 – May 2009**
- **Wave Observations from Space**
- **„Parametric Rolling“ occurred by accident**

# Conclusions (1)

- **RV „Polarstern“ experienced „Parametric Rolling“ on March 7<sup>th</sup>, 2009**
- **A Cross Sea was observed by Wave Radar and from Satellite and forecast by Wave Models.**
- **Forecasting Rolling Events seems to be possible**



# Lateral Stability of a Ship

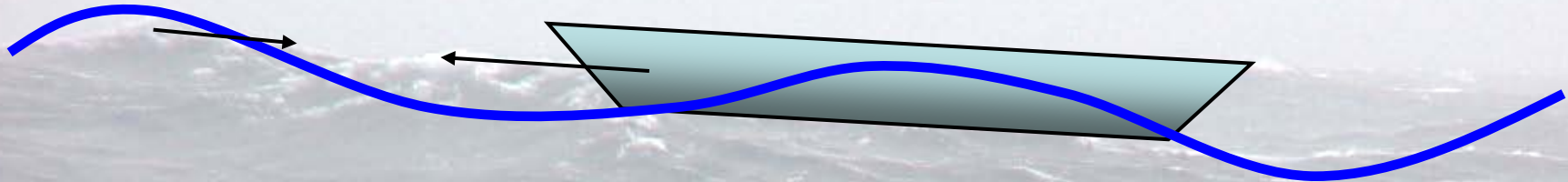


Eigenperiod of Rolling :  $T_R = f B (GM_0)^{-1/2}$

# Parametric Rolling

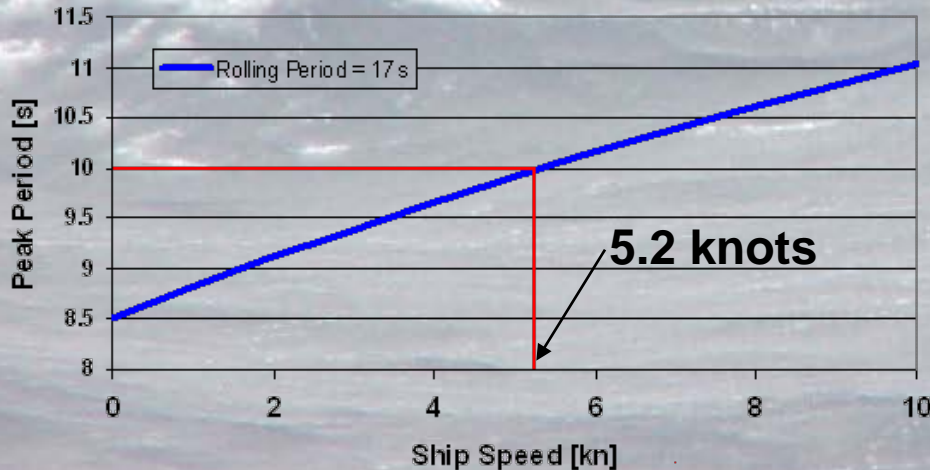
occurs due to

## Periodic Loss and Gain of Lateral Stability



- ✓ Waves must be high enough to cause heavy pitching
- ✓ Wave length must be of the order of one to two ship lengths
- ✓ **Period of Encounter** = multiple of half the Rolling Period

$$T_E = (1 / T_p - V_s \cos(\mu) / L_p)^{-1} \quad \stackrel{!}{=} \quad n/2 T_R$$



**Resonance Condition  
in a Heading Sea ( $\mu=180$  ,  $n=1$ )**

$$T_R = 17 \text{ s}$$

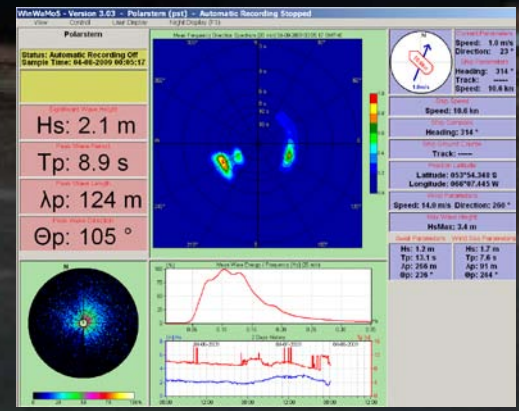
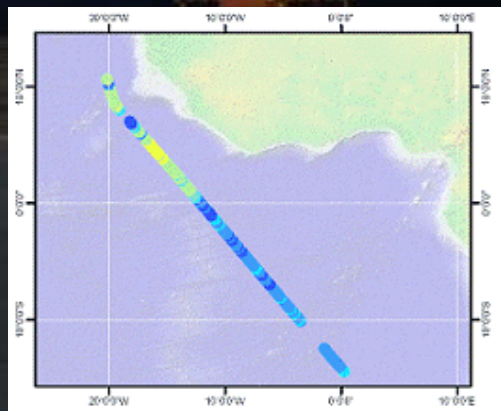
$$T_E = 8.5 \text{ s}$$

The ship must pitch twice for every roll





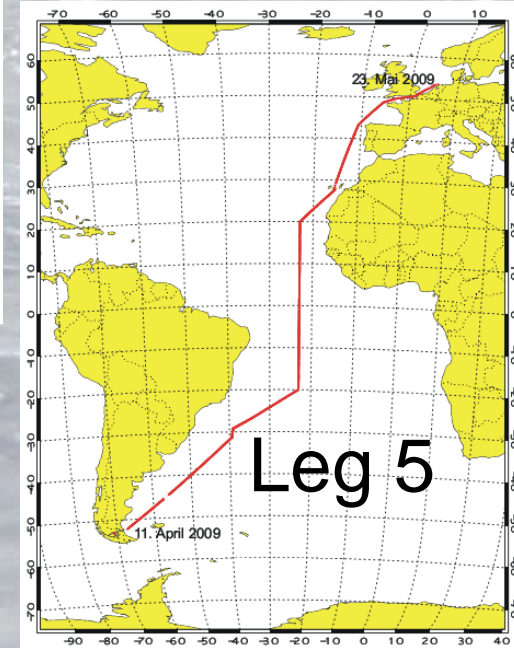
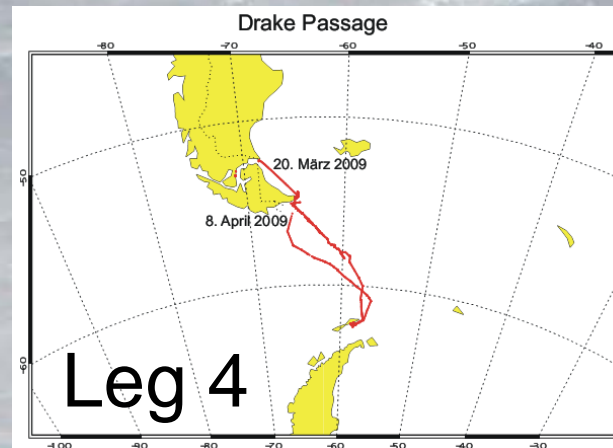
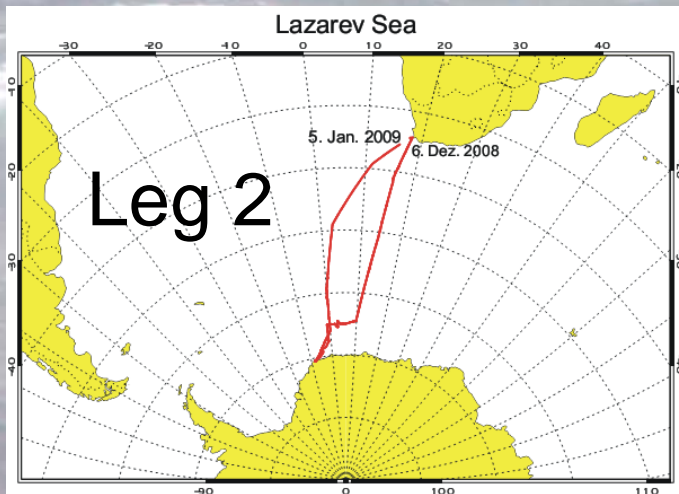
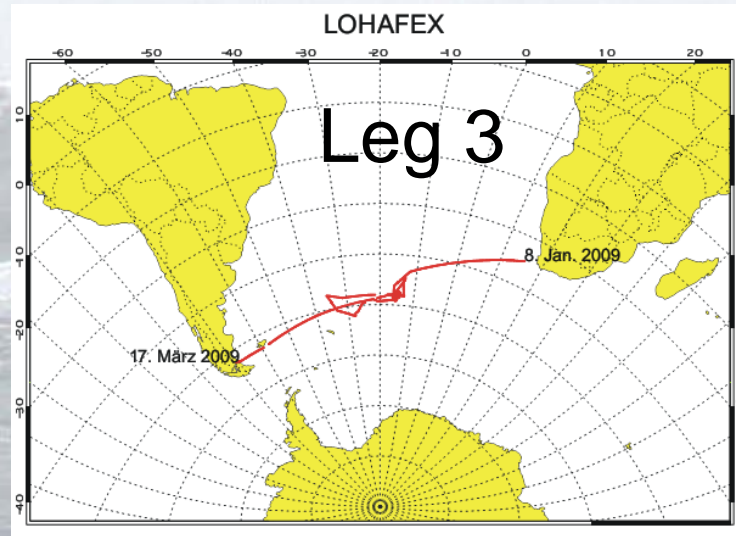
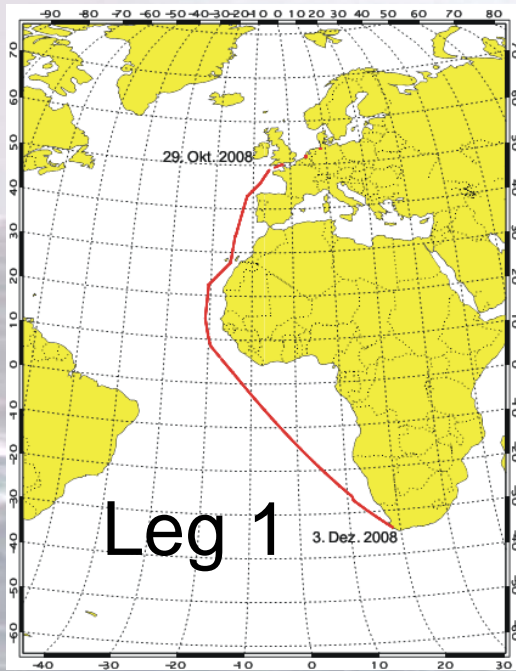
Radar Antenna





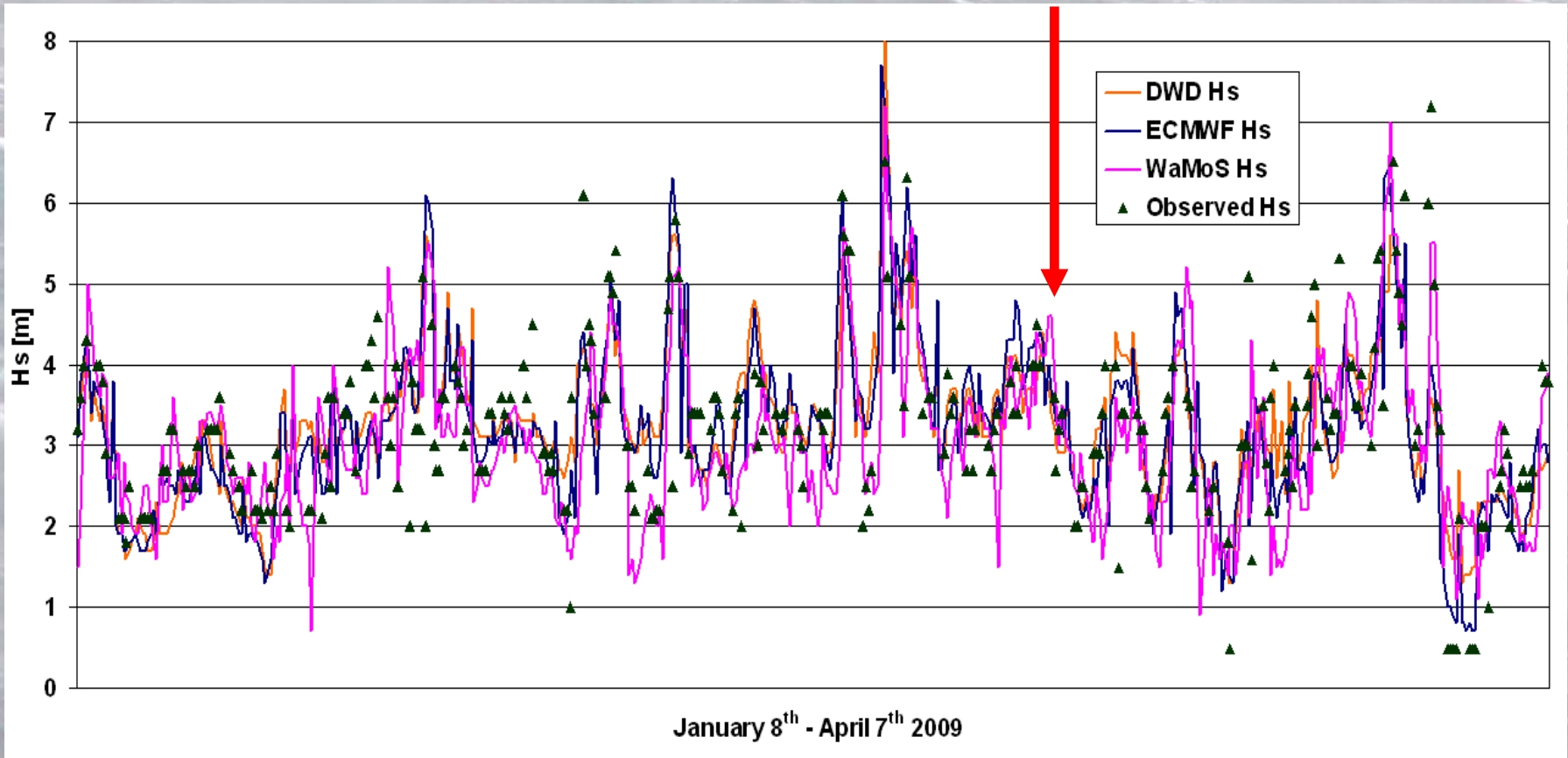
# „Polarstern“ Expedition ANT-XXV

## 2008/2009



# Significant Wave Height Comparison between Wave Models, WaMoS and Visual Observations

Rolling Event  
on March 7<sup>th</sup>, 2009

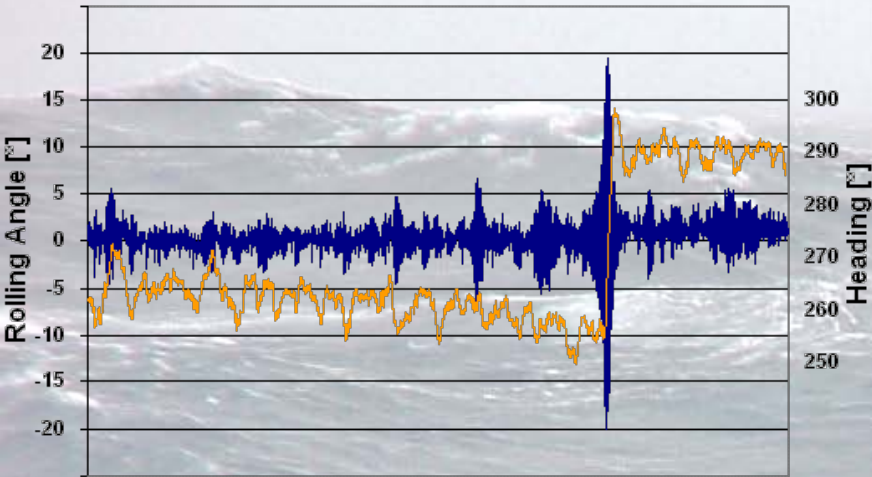




# The Rolling Event

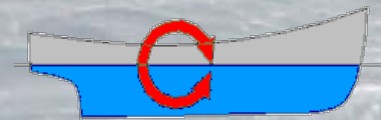


Rolling Angle and Gyro Heading

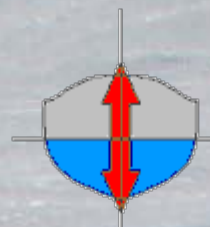


Roll

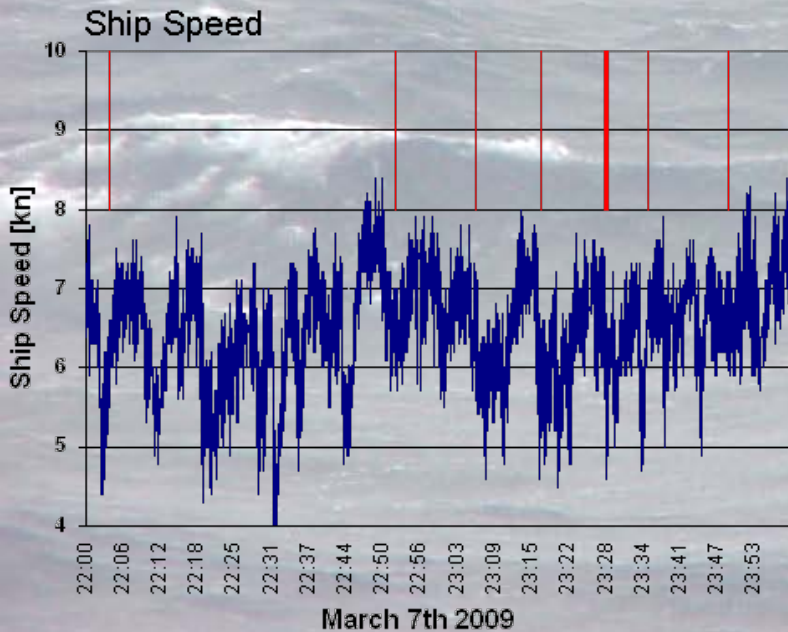
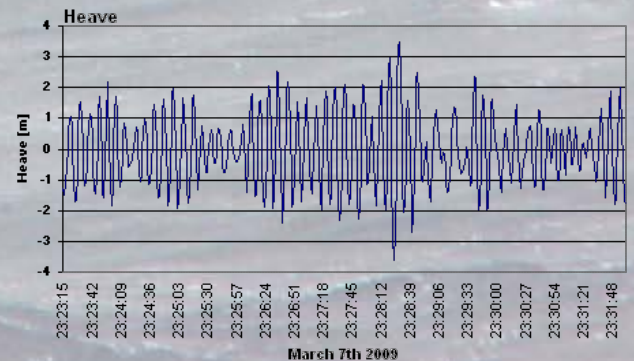
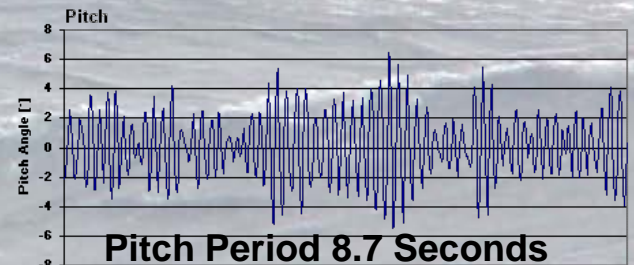
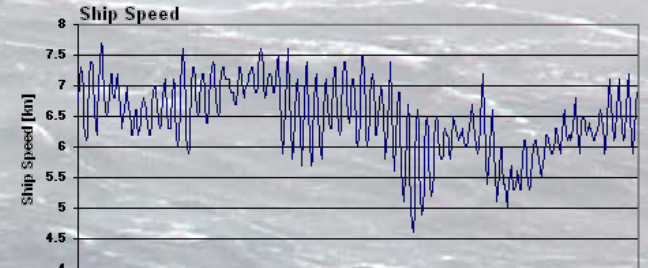
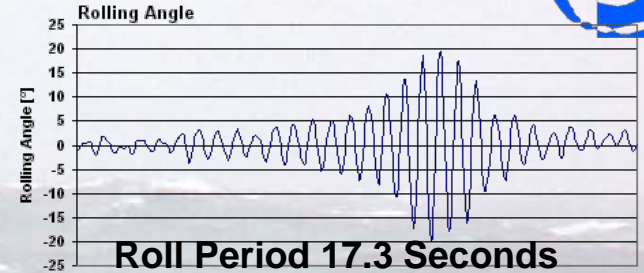
Speed



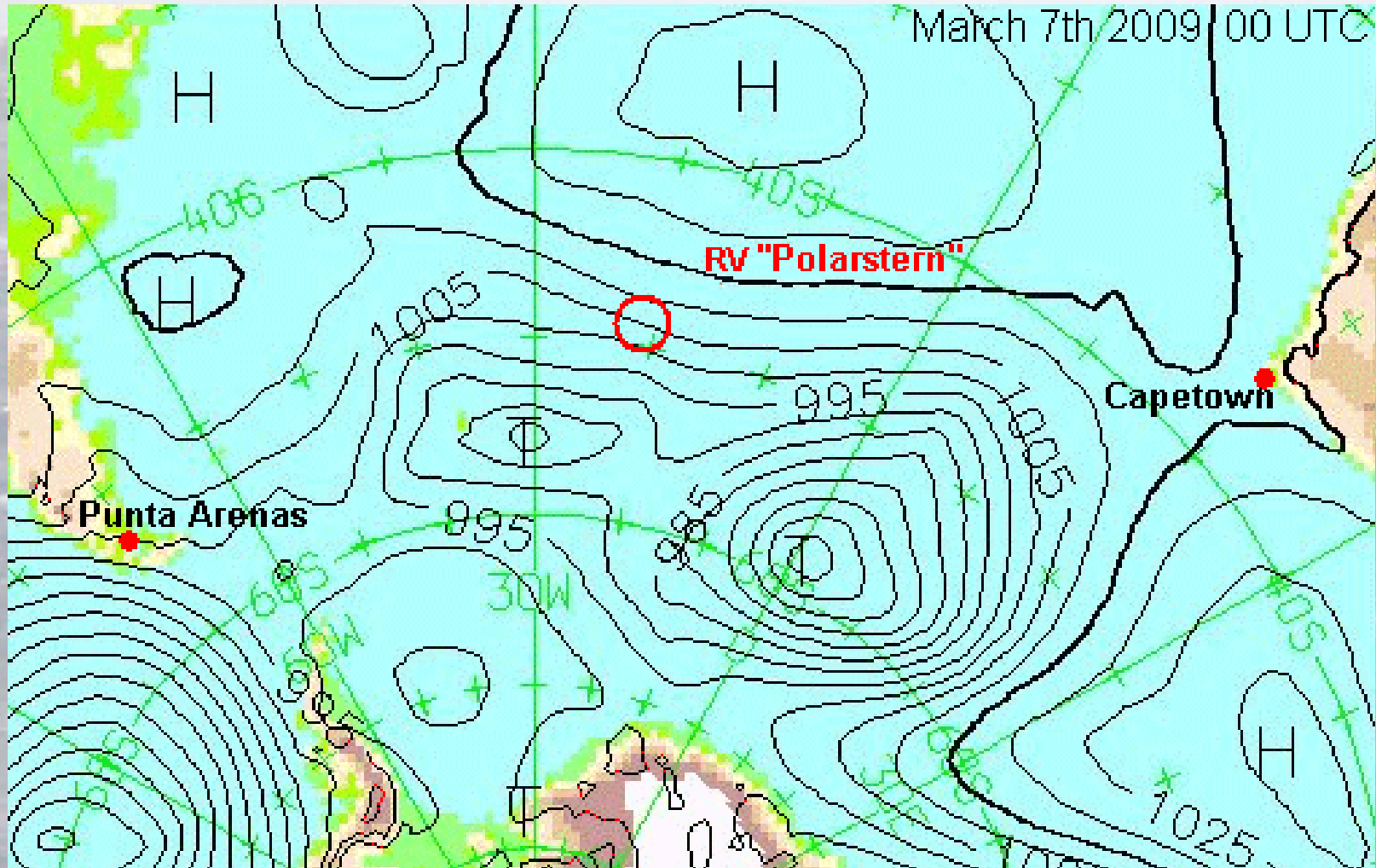
Pitch



Heave



# Synoptic Situation on March 7<sup>th</sup>, 2009

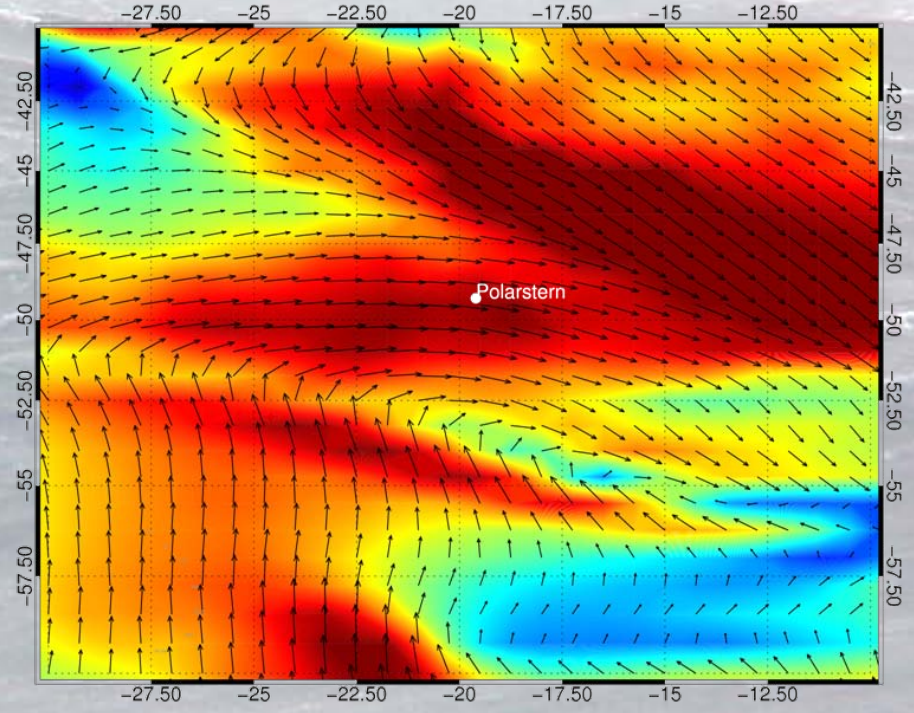
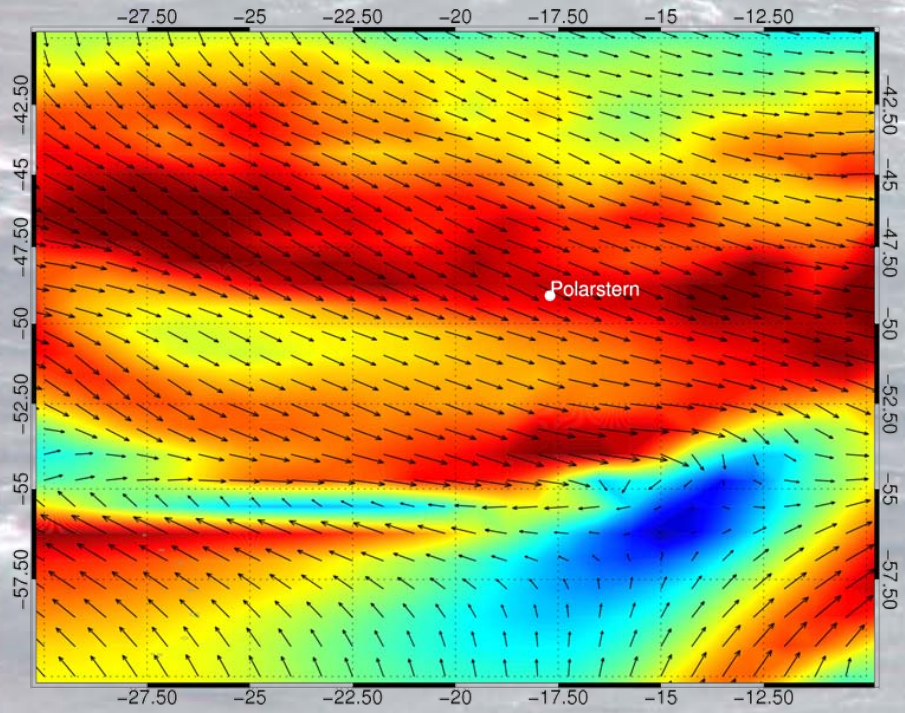




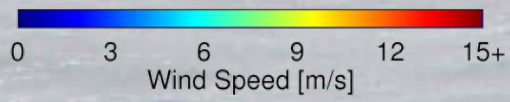
# Wind Field of DWD Global Wave Model on March 7<sup>th</sup> , 2009

06:00 UTC

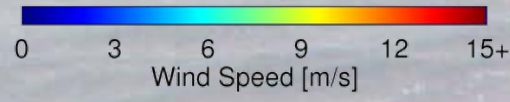
18:00 UTC



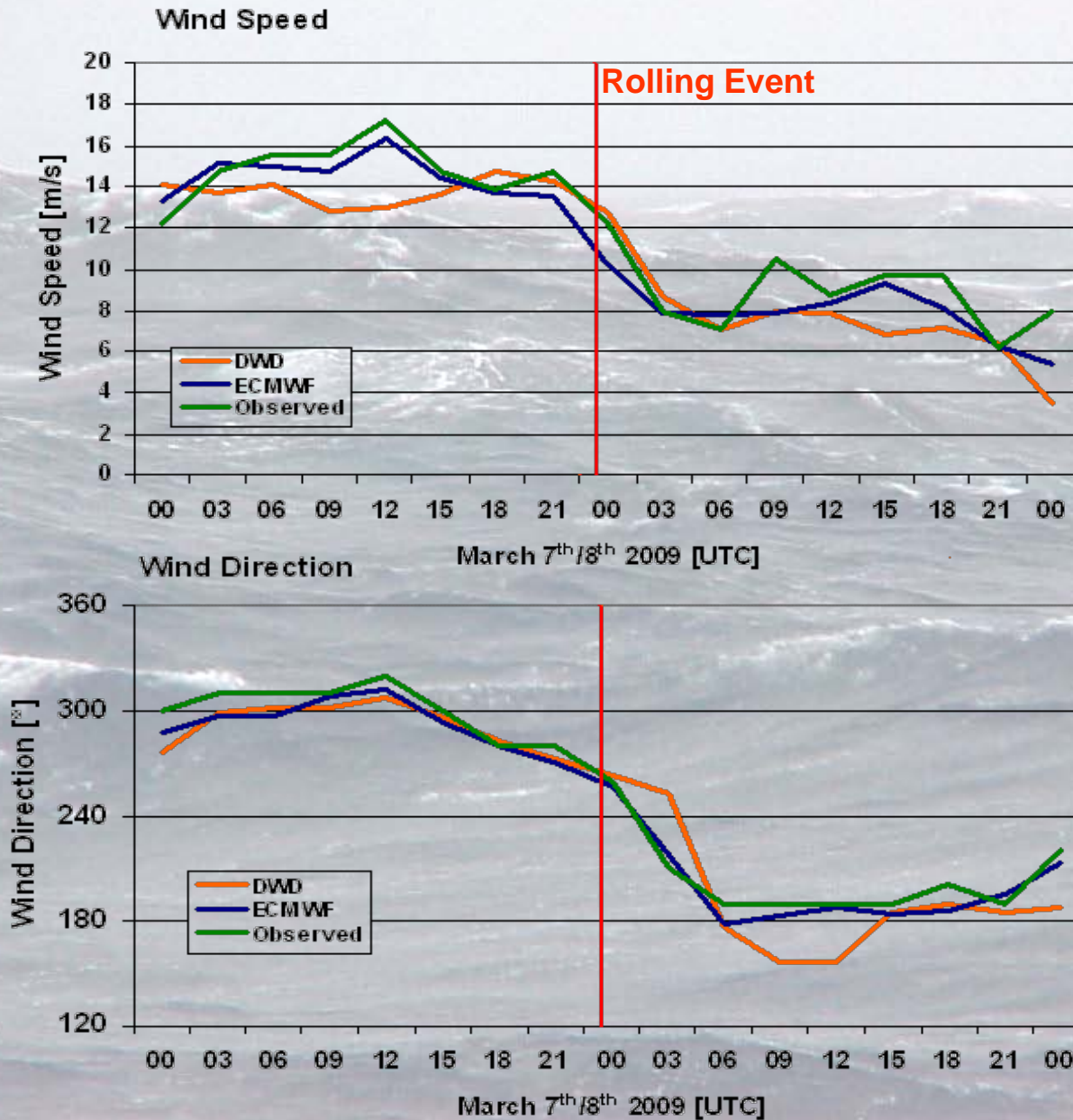
→  
15 m/s



→  
15 m/s



# Wind observed and forecast

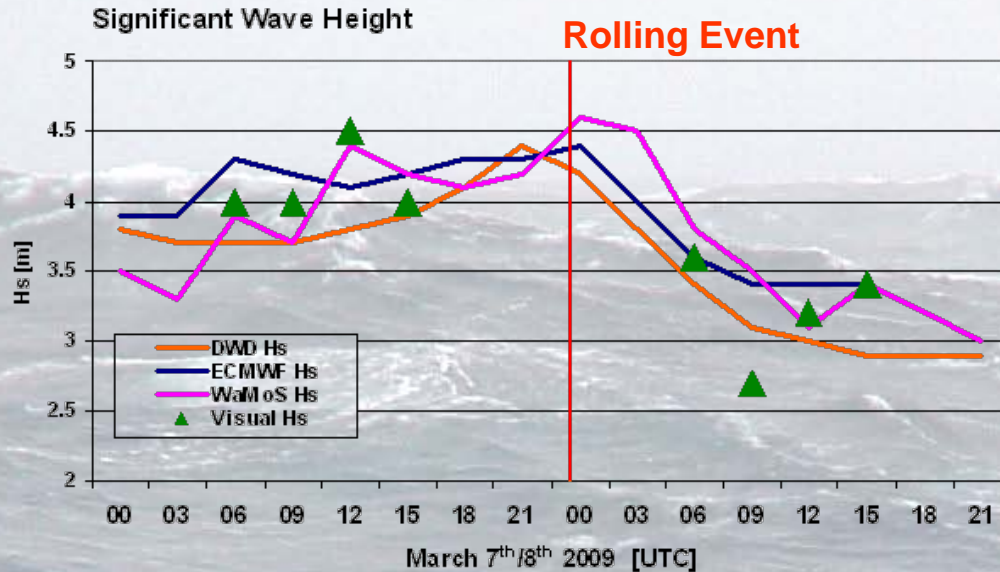


**DWD**  
**ECMWF**  
**Anemometer**  
(reduced to 10m)



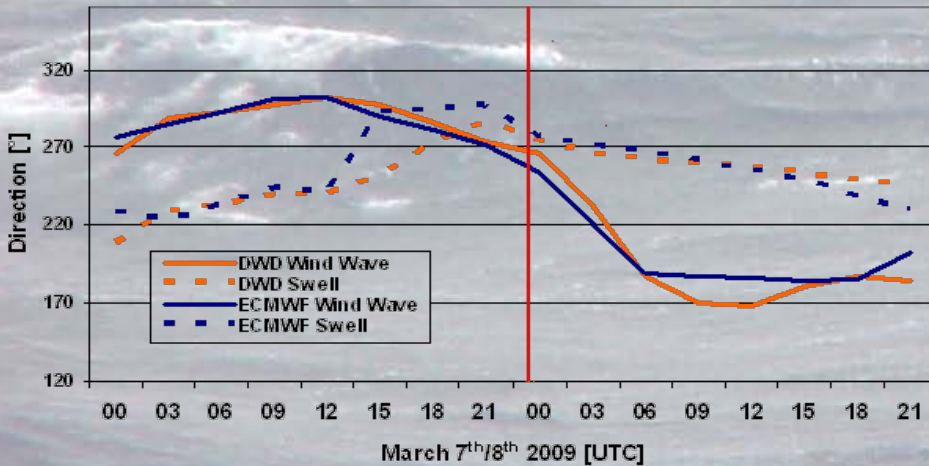


# Waves observed and forecast

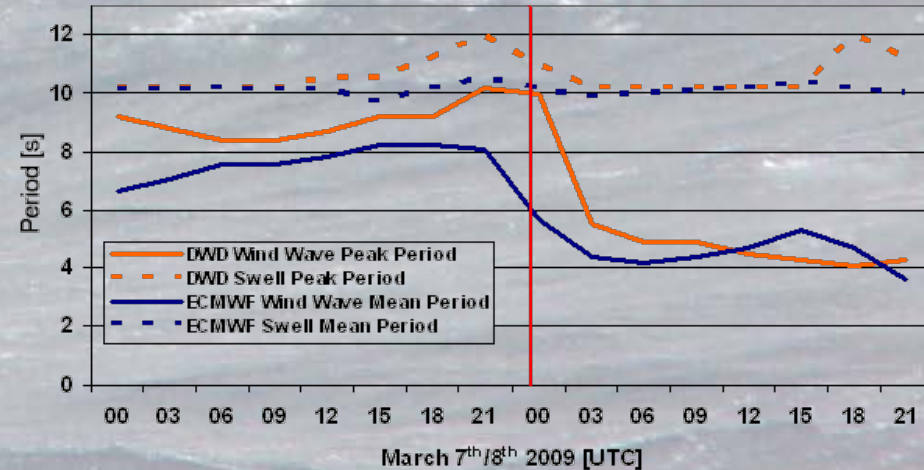


**DWD**  
**ECMWF**  
**WaMoS**  
**VISUAL**

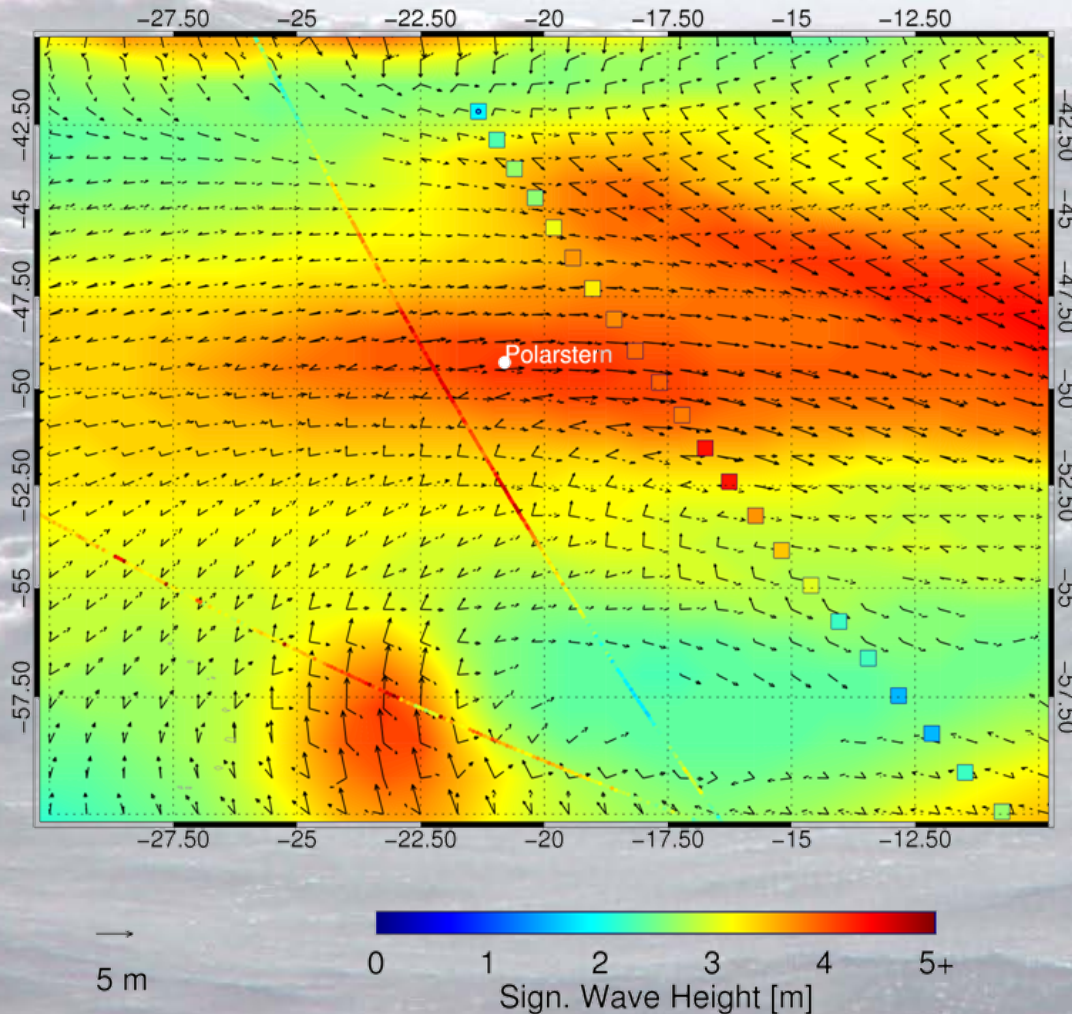
**Wave Direction**



**Wave Period**



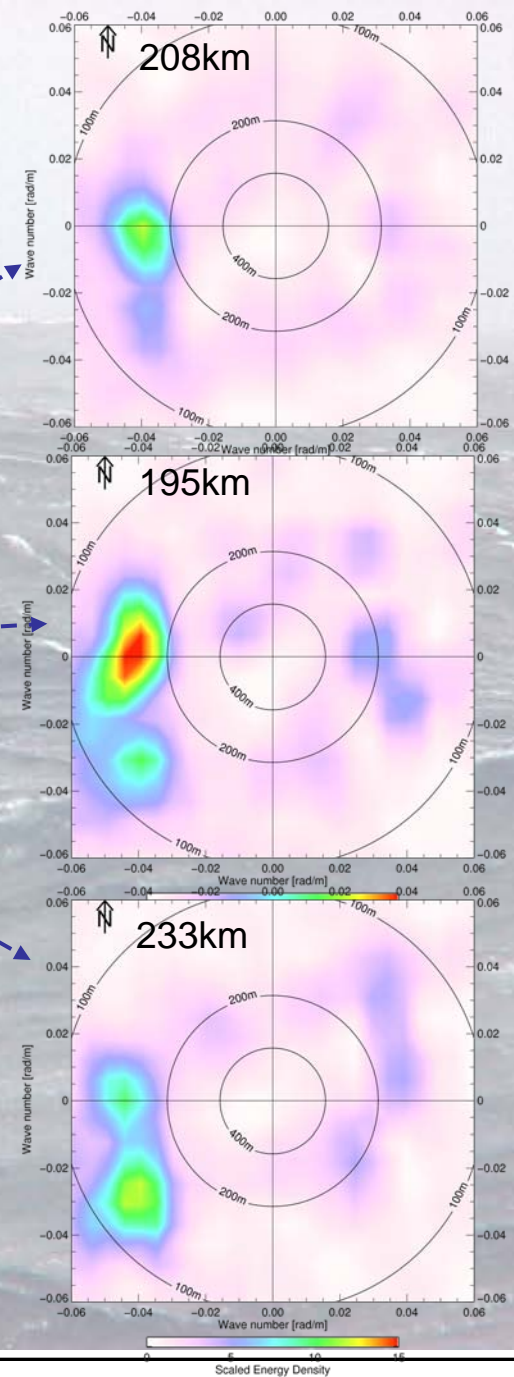
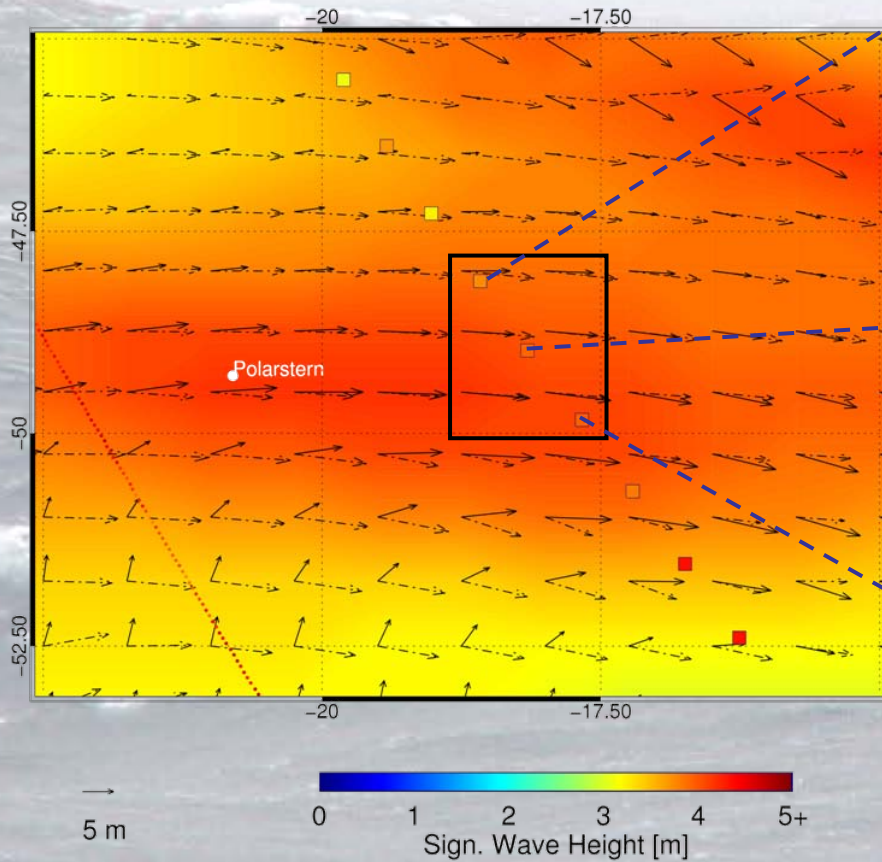
# Wave Field of DWD Global Wave Model on March 8, 2009 at 0:00 UTC



Measurements of **SWH** derived  
from **ENVISAT**  
Radar Altimeter and  
ASAR wave mode

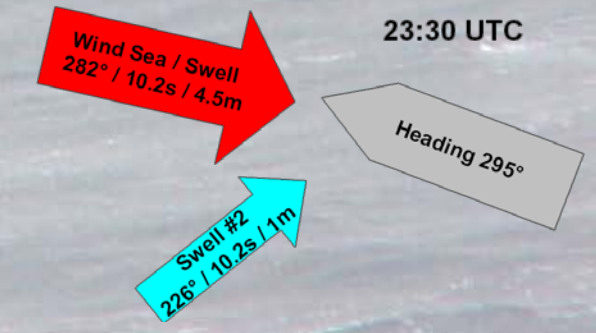
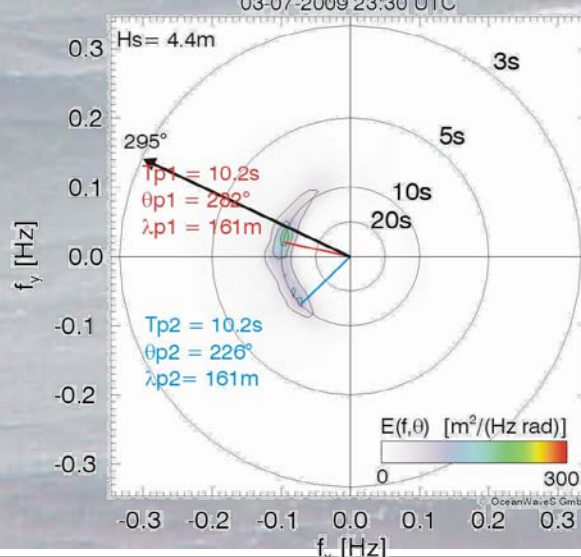
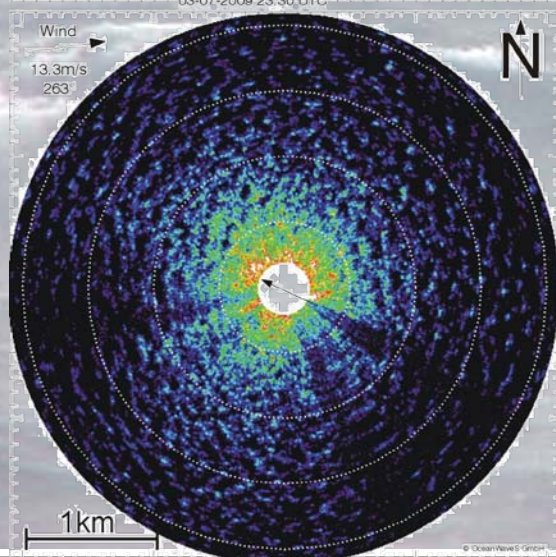
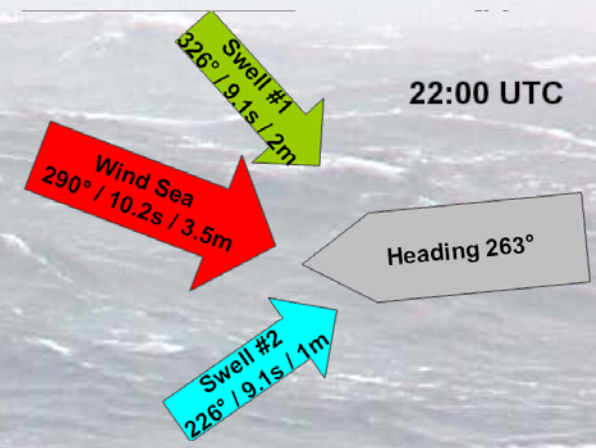
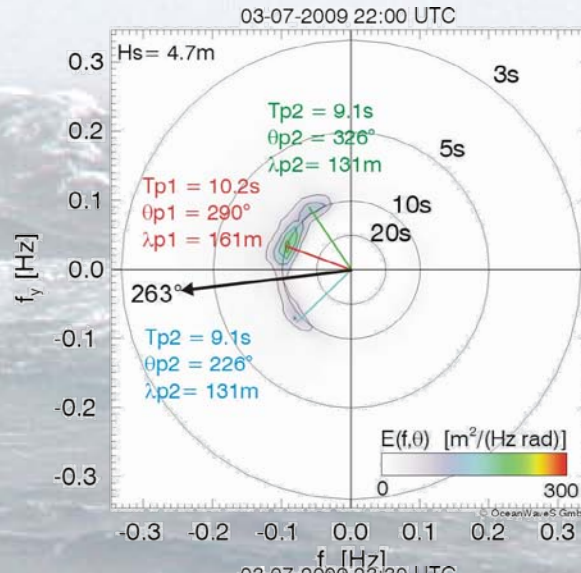
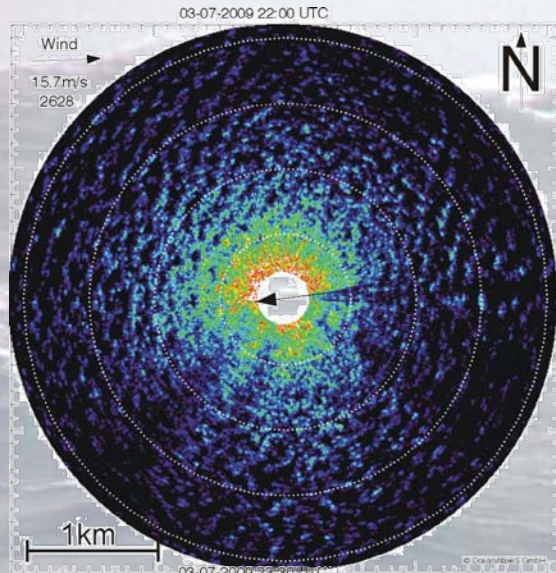


# Imaginary parts of ENVISAT ASAR Cross Spectra near to the “Polarstern” shortly after the Rolling Event.

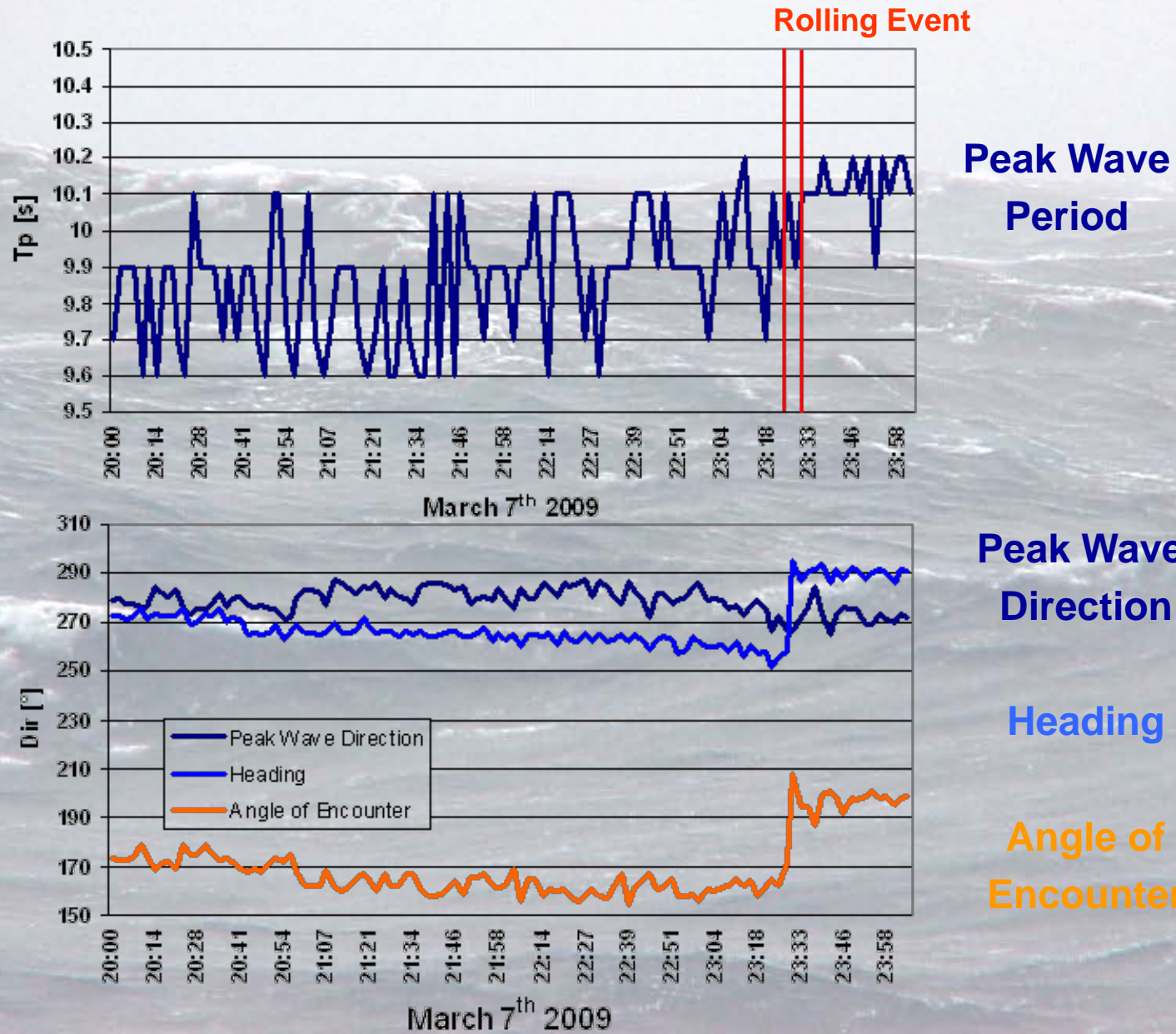




# „WaMoS“ Wave Spectra



# WaMoS 2-min-running mean data

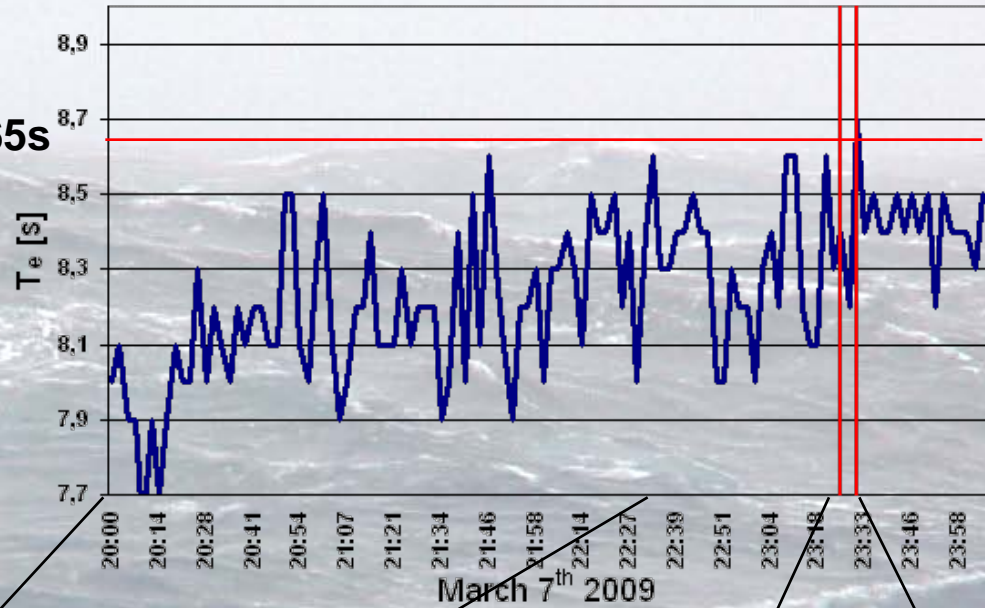




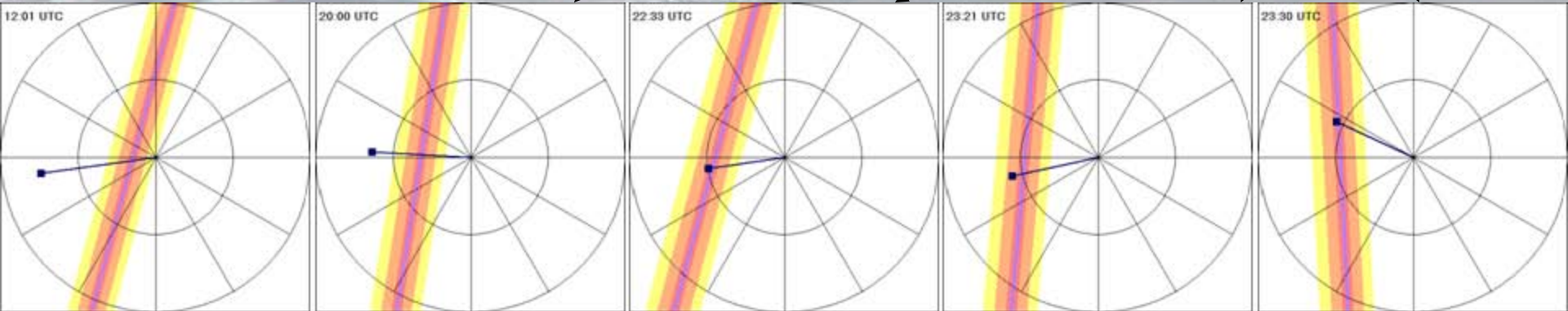
# Period of Encounter

Critical Period 8.65s

Wave Radar  
(2-min-running mean)

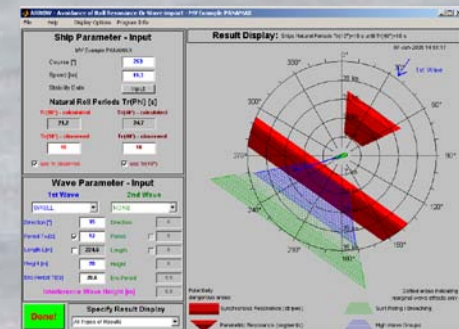
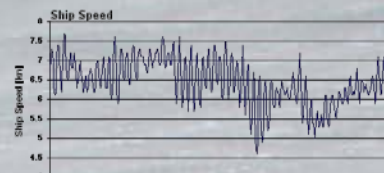
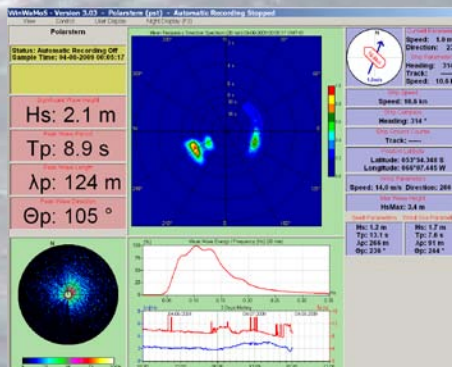


Resonance Diagrams



# Conclusions (2)

- The Rolling Event was of the „parametric type“
- Parametric Rolling is predictable and avoidable by Monitoring
  - Sea Condition (**Wave Radar + Model Forecasts**)
  - Ship Motion (**Sensors + Accelerators**)
  - Resonance Condition (**Intelligent Software**)





Thanks for your attention

